

# 17-Stand Alone Wind Energy Systems

ECEGR 452  
Renewable Energy Systems

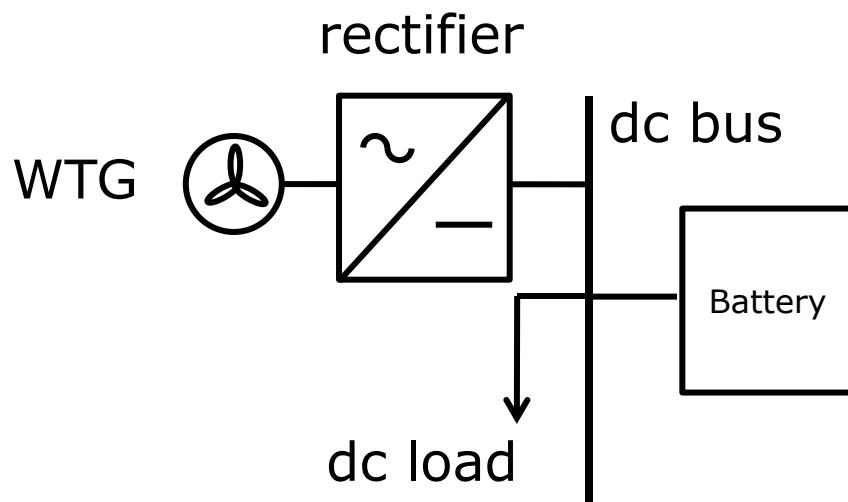


# Overview

- Topology
- Modeling
- Power Output
- Rotational Dynamics



# Basic System Topology



- \*rectifier may be included in WTG
- \*controls not shown
- \*inverter and ac load not shown



# Stand Alone Wind Turbines

- Almost always less than 100kW
  - Typically < 10kW
- Permanent Magnet Synchronous Generators (PMSG)
  - Direct drive (no gearing)
  - AC output (assume three phase)
  - Rectifier
  - Battery



# Farday's Law

- PMSG: voltage induced according to Lenz's Law

$$\oint_C \mathbf{E} \cdot d\ell = - \int_s \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{s}$$

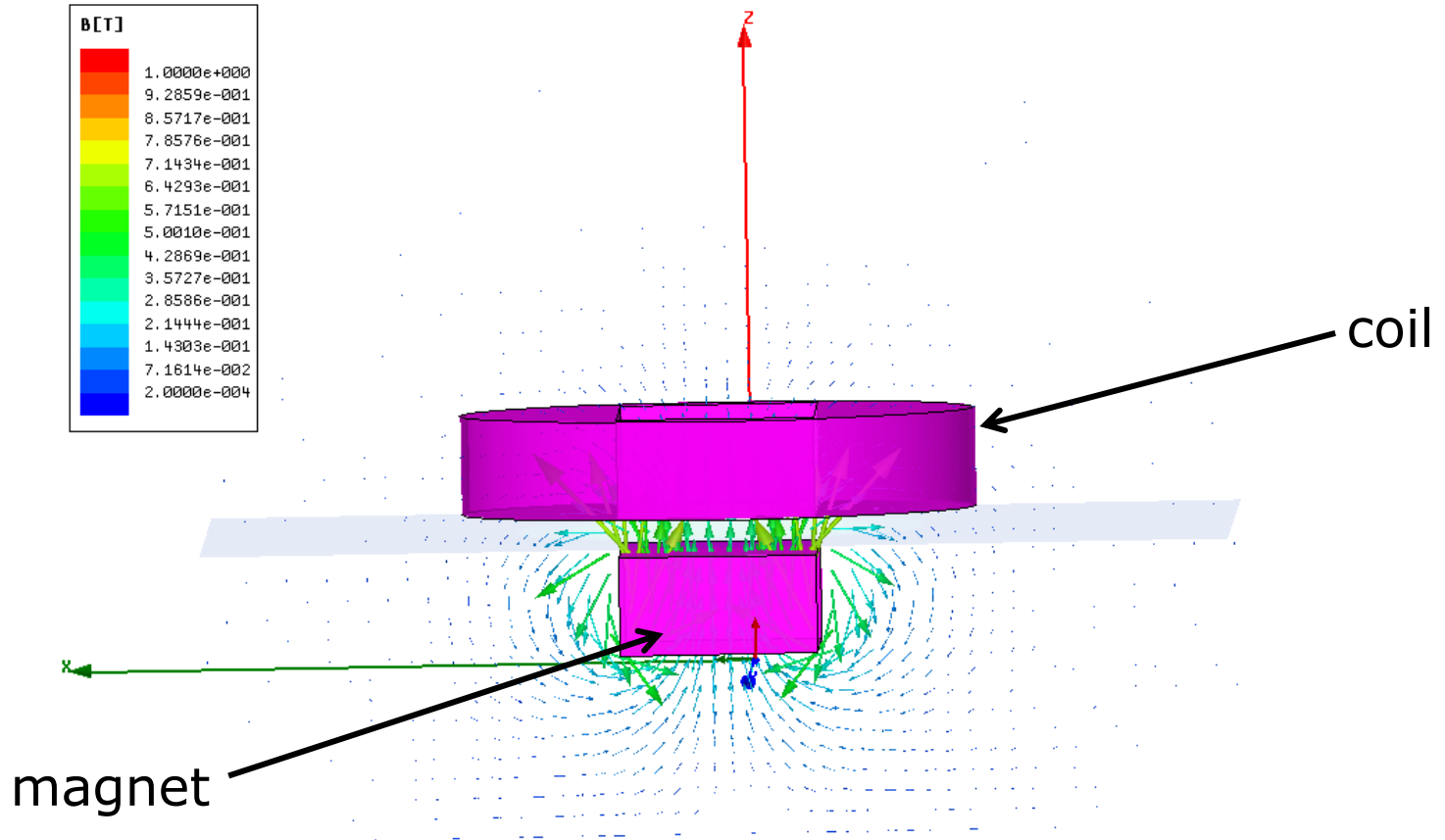
$$e = - \int_s \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{s} = - \frac{d\Phi}{dt}$$

- Where  $e$  is the induced electromotive force (emf)
- For multiple turns ( $N$ )

$$e = -N \frac{d\Phi}{dt} \quad \longleftarrow \text{Need time-varying magnetic flux}$$

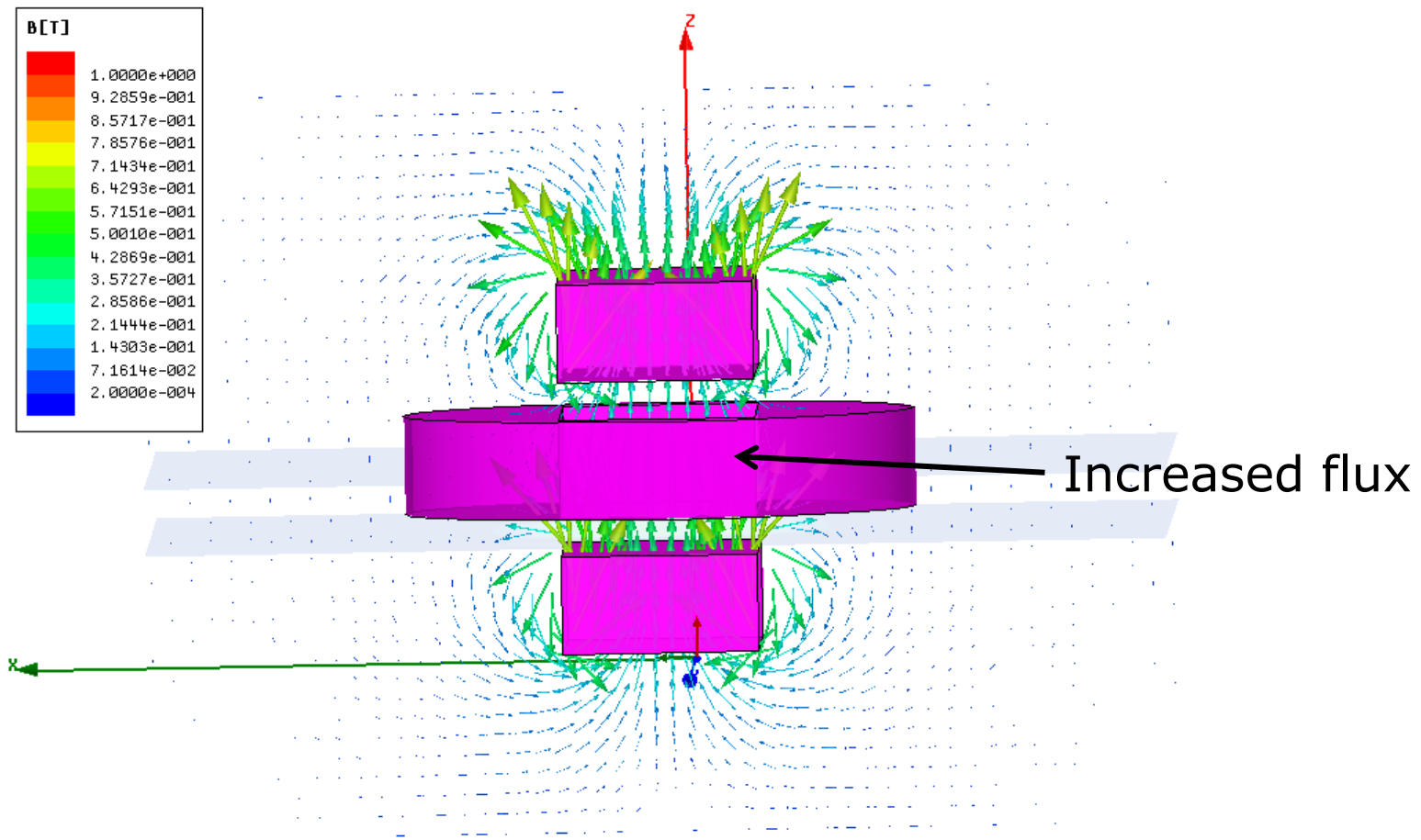


# PMSG



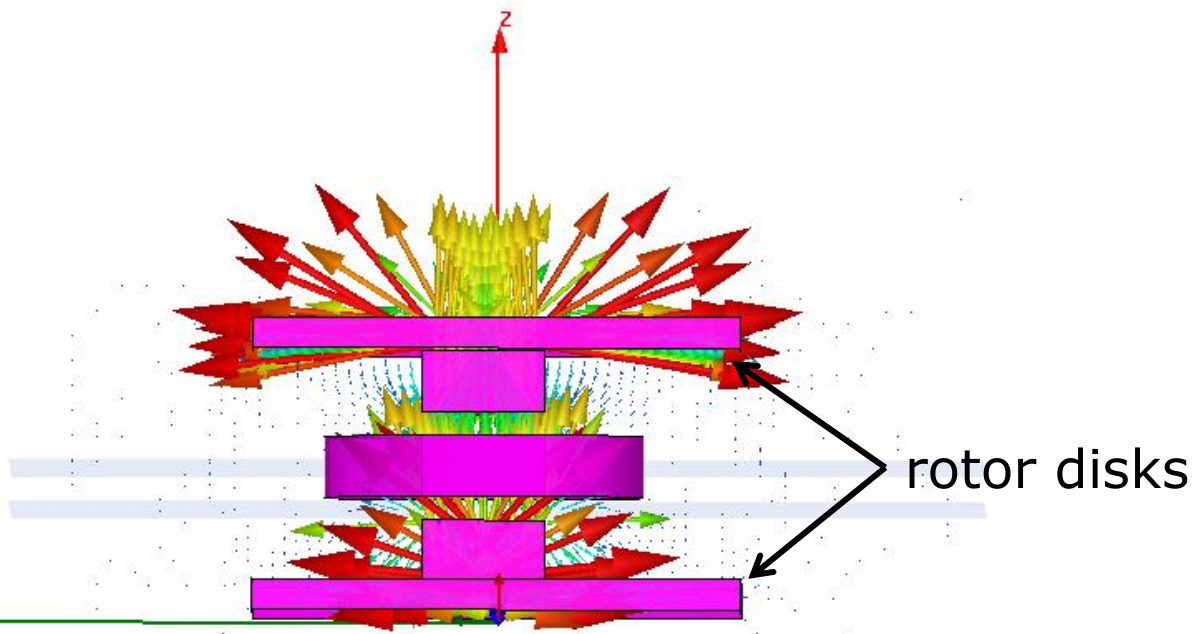
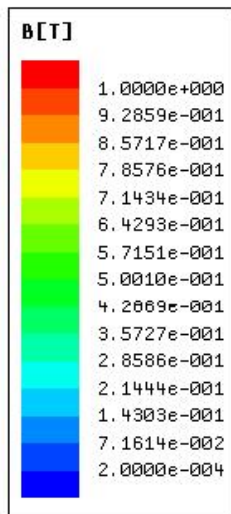


# PMSG (two magnets per pole)





# PMSG (with rotor disks)



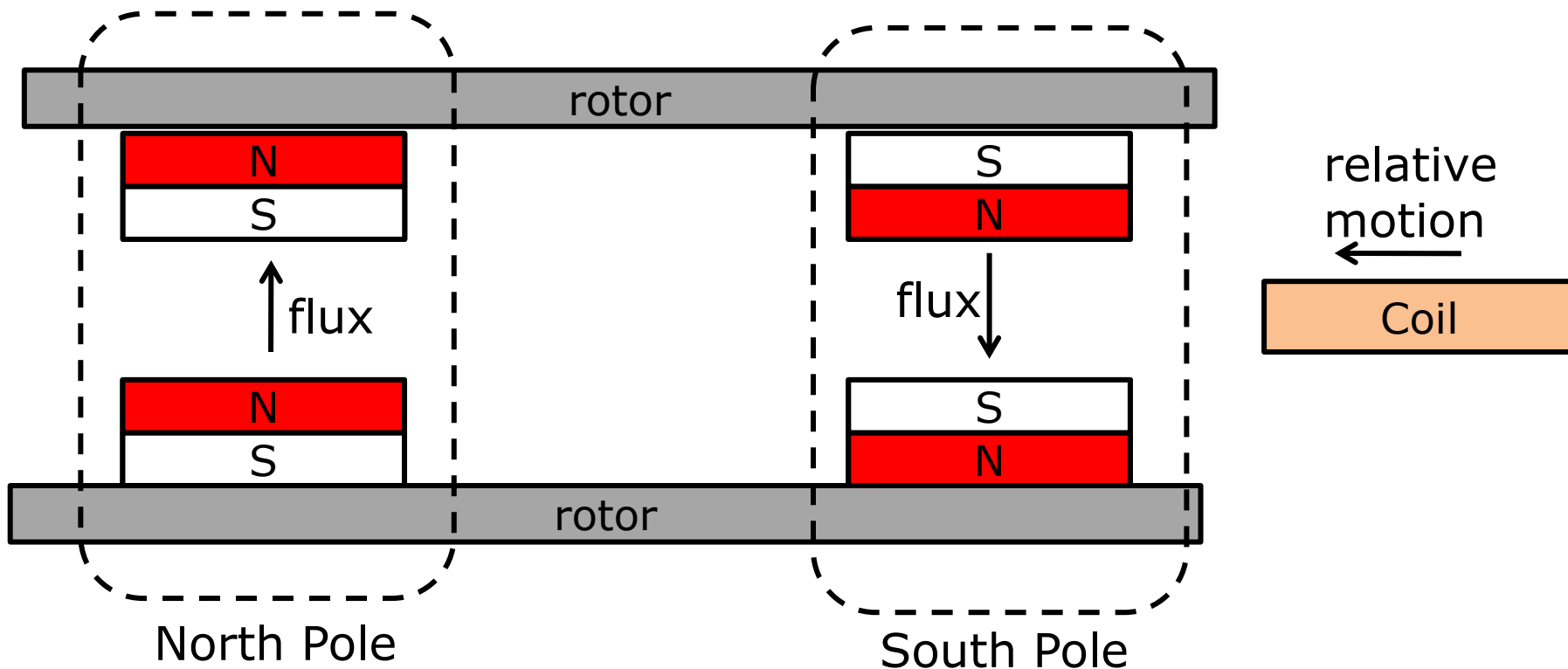
Large amount  
of flux





# PMSG (multi-pole)

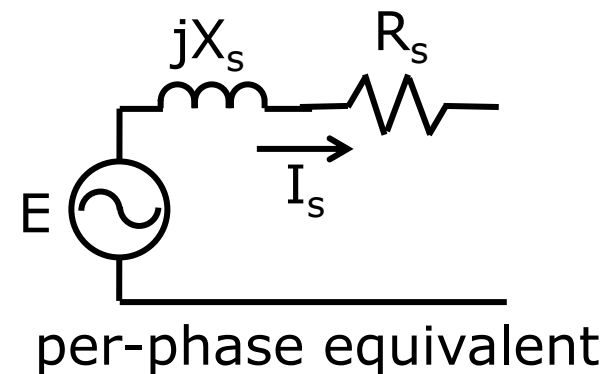
- For every pair of poles, that the coil passes by, one sinewave is induced





# Wind Turbine Generator (WTG)

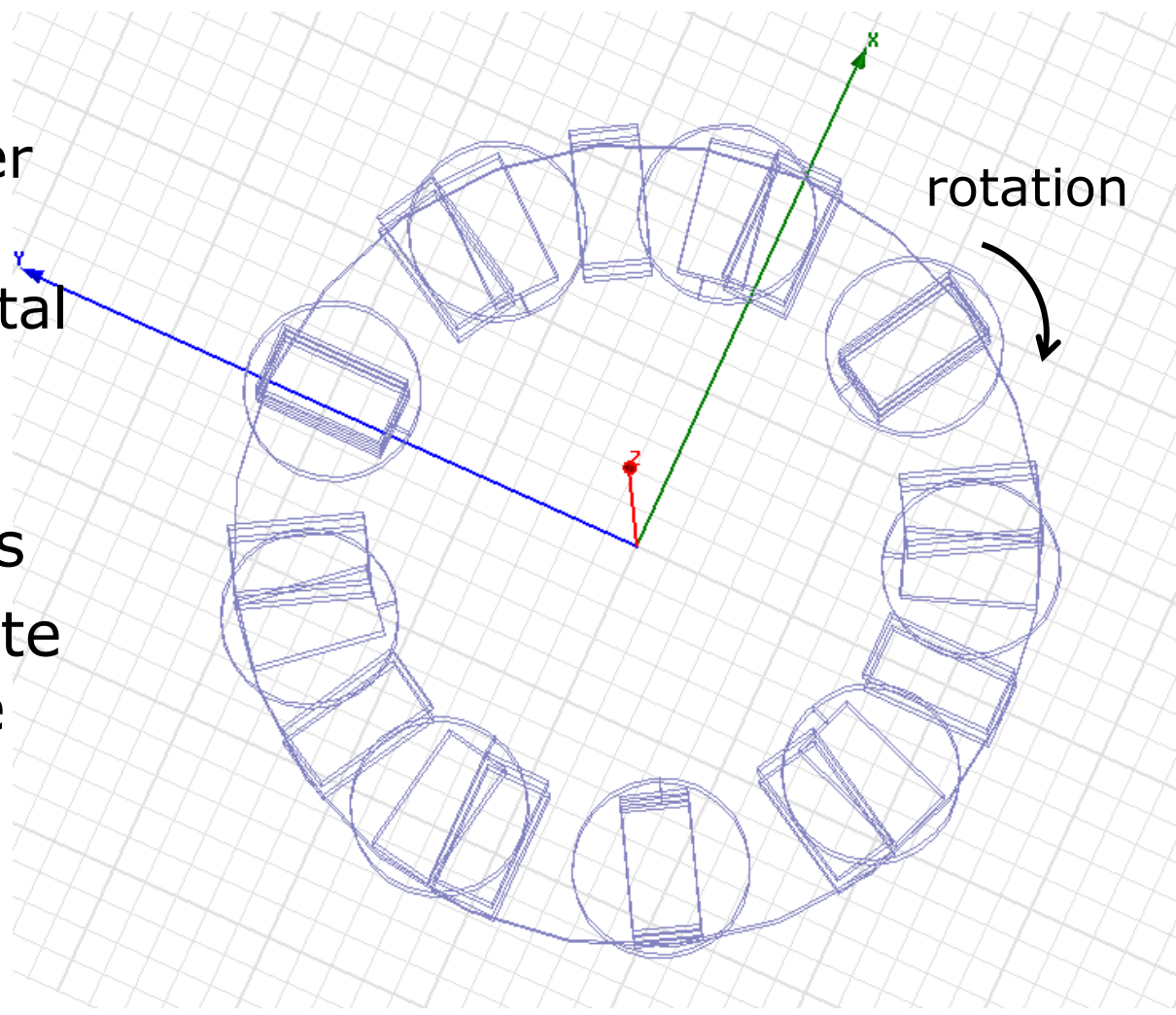
- $E = \omega_m \times A \times C \times N \times P \times B$ 
  - E: induced emf (V RMS)
  - $\omega_m$  : rotor shaft speed (rad/s)
  - A: cross-sectional area of stator coils (m<sup>2</sup>)
  - C: number of series-connected coils
  - N: number of turns in each coil
  - P: number of pole pairs
  - B: flux density (Tesla RMS)
- $L_s$ : Series synchronous inductance (H)
- $R_s$ : Series resistance (Ohm)





# Wind Turbine

- 6 pole pairs
  - 12 magnets per rotor
  - 24 magnets total
- 1 mechanical period = 6 electrical periods
- Magnets alternate N-S around face

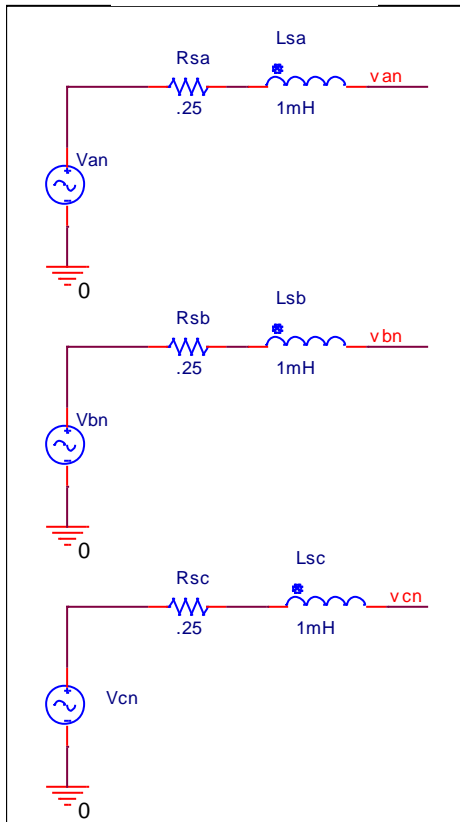




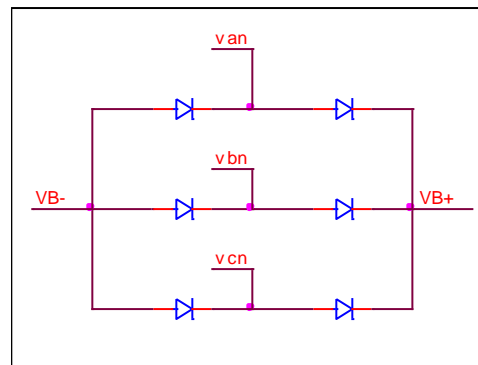
# Basic System Topology

3-phase generator

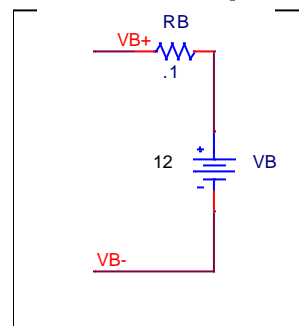
## WTG



## Rectifier



## Battery



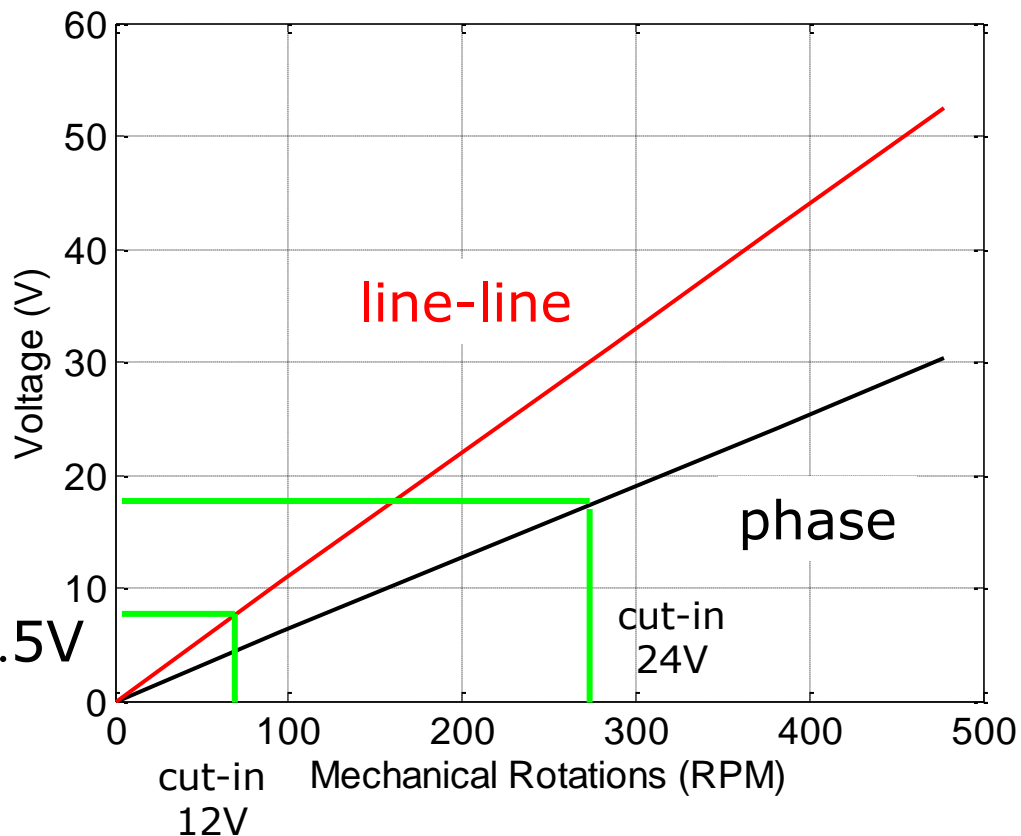


# Operation

- Let  $E = \omega_m \times A \times C \times N \times P \times B = E = \omega_m \times K_m$ 
  - A: 0.0013 m<sup>2</sup>
  - C: 3 series-connected coils
  - N: 70 turns
  - P: 6 pole pairs
  - B: 0.37 Tesla
- Therefore:  $K_m = 0.6 V_{rms}/rad/s$
- $X_s$ : 0.001 H
- $R_s = 0$  Ohm (lossless)



# Open Circuit Terminal Voltage (RMS)

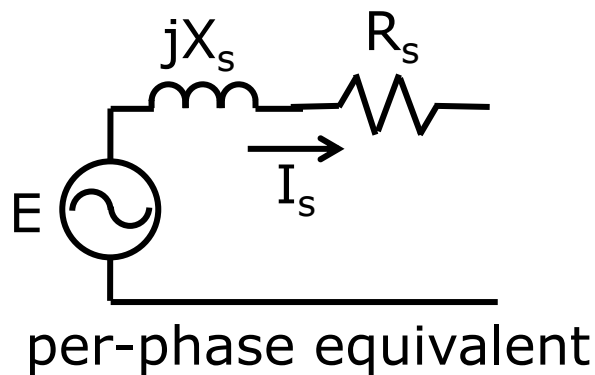


Note:  $\frac{12}{\sqrt{2}} \approx 8.5V$



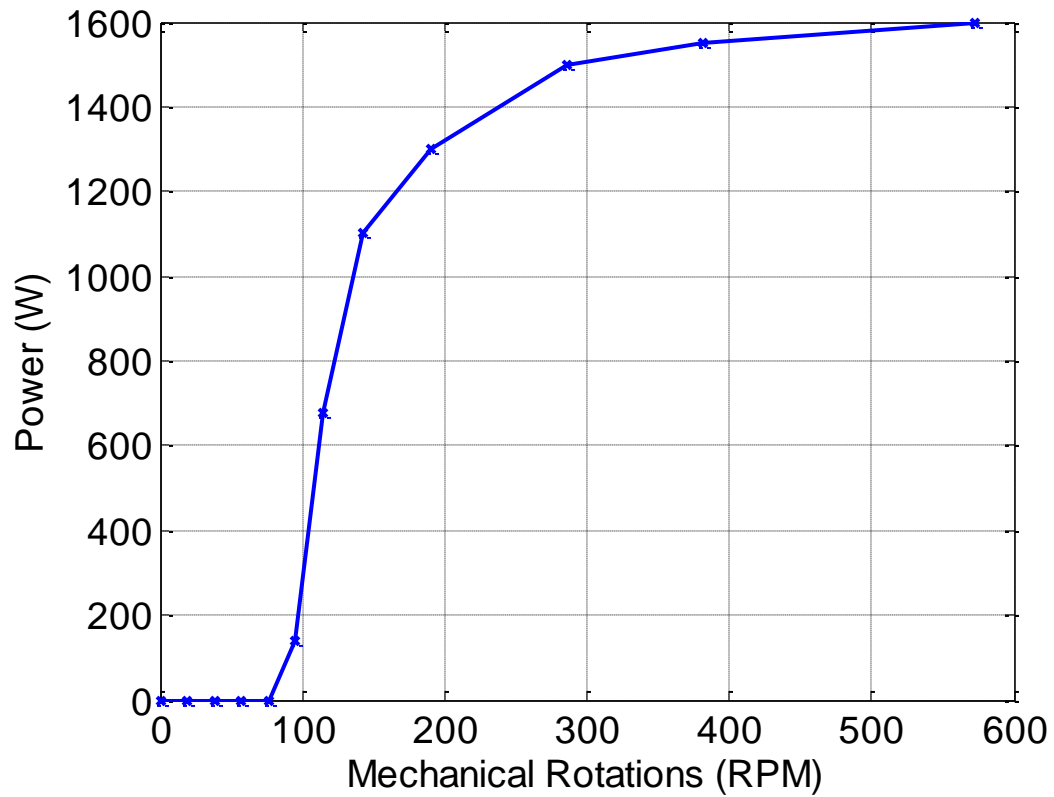
# Operation

- If voltage ( $E$ ) increases linearly with RPM, how does the power to the battery increase?
  - Non-linear
  - As  $E$  increases, so does  $jX_s$





# Power to Battery (12V)







# Rotational Dynamics

- Recall
  - Power = torque x angular velocity
- How do we determine the rotor speed and net torque of a wind turbine?



# Rotational Dynamics

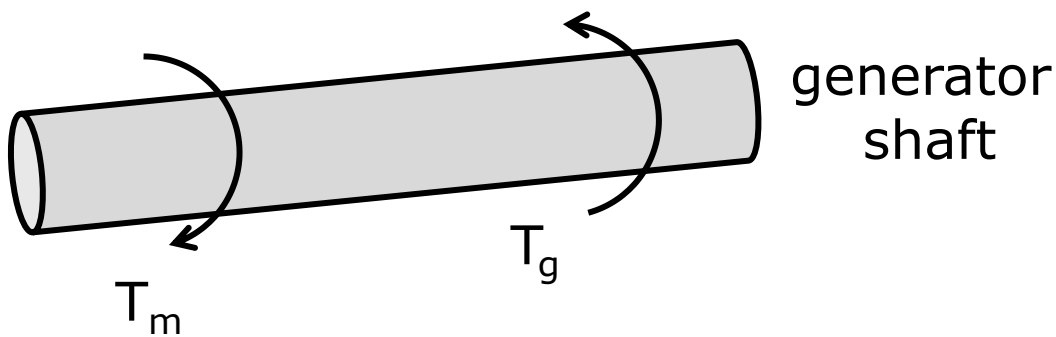
- Assume
  - Direct coupling of generator and rotor
  - No rotor friction
- From rotational dynamics:
$$T_m - T_g = J \frac{d\Omega}{dt}$$
  - Where:
  - $T_m$ : torque on shaft caused by wind (Nm)
  - $T_g$ : torque on shaft caused by electrical load, electromagnetic in nature (Nm)
  - $J$ : wind turbine moment of inertia
  - $\Omega$ : rotor angular velocity (rad/s)



# Rotational Dynamics

- $T_m = T_g$ 
  - No change in rotor speed
- $T_m > T_g$ 
  - rotor speed increases
- $T_m < T_g$ 
  - rotor speed decreases

$$T_m - T_g = J \frac{d\Omega}{dt}$$



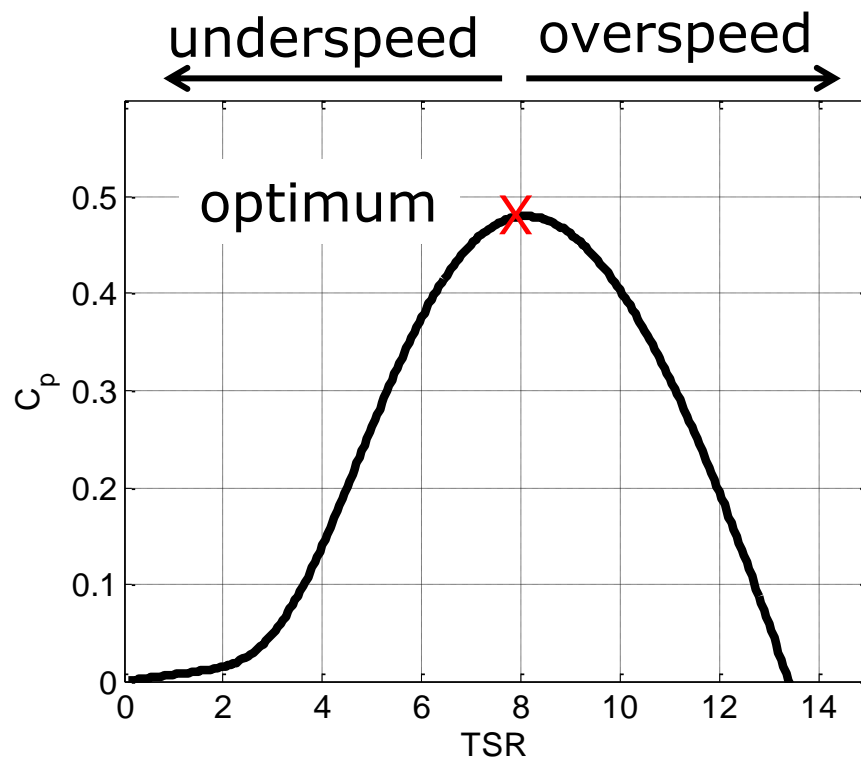


# Rotational Dynamics

- Mechanical power from the wind turbine:

$$P_m = \frac{1}{2} C_p(\lambda, \beta) A \rho v^3$$

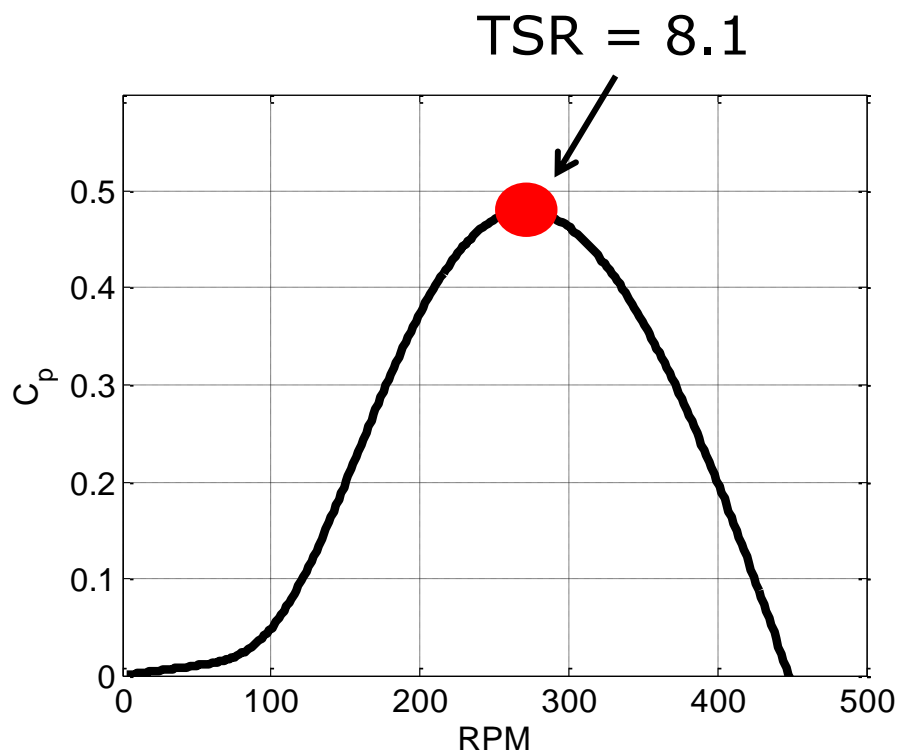
- $\lambda$ : tip speed ratio
- $\beta$ : blade pitch (degrees)





# Rotational Dynamics

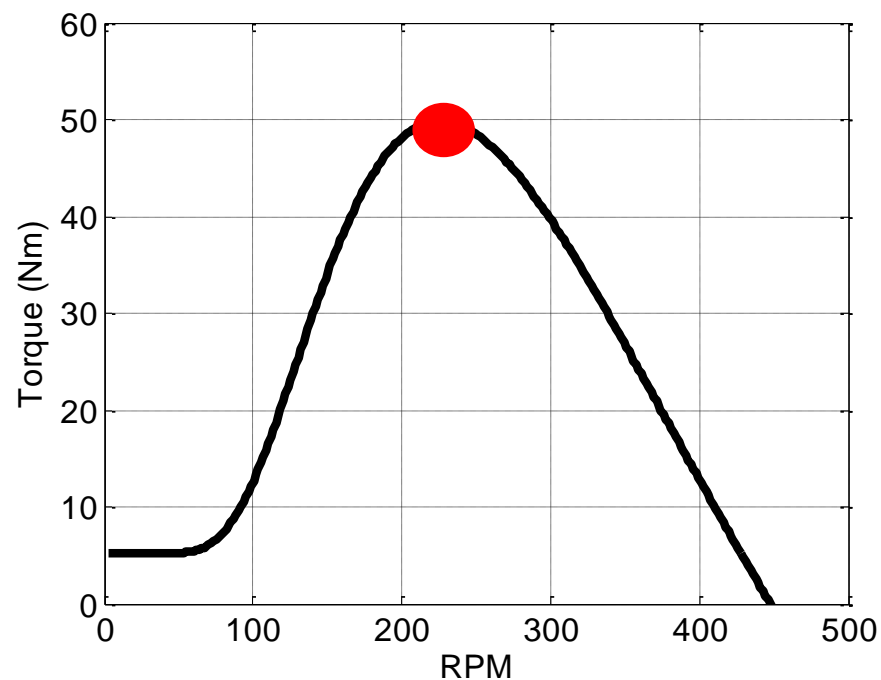
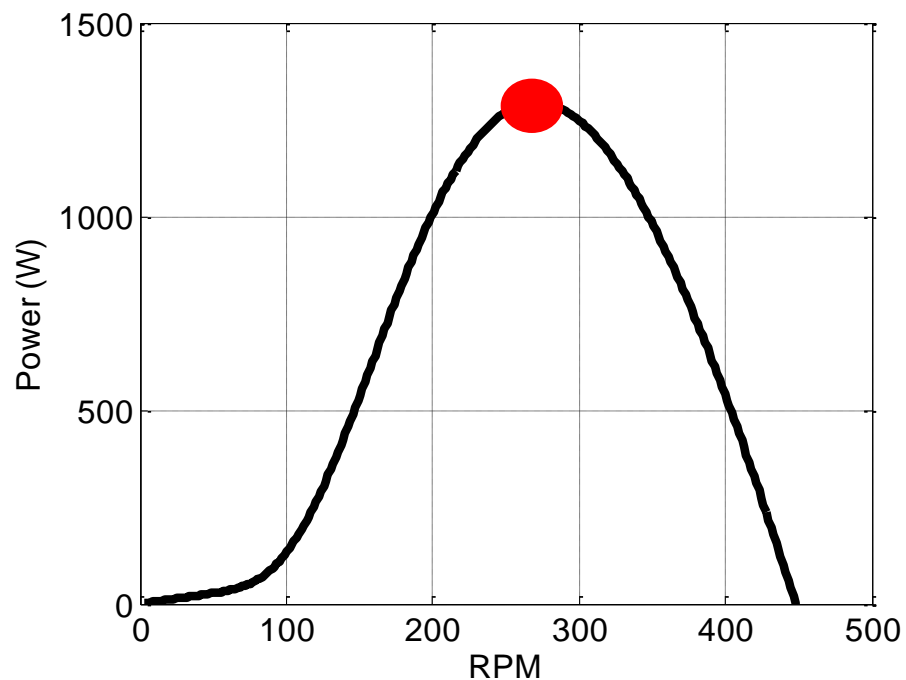
- Let  $v = 7\text{m/s}$  and  $r = 2\text{m}$  (rotor radius)
- Assume turbine is operating at optimal TSR





# Rotational Dynamics

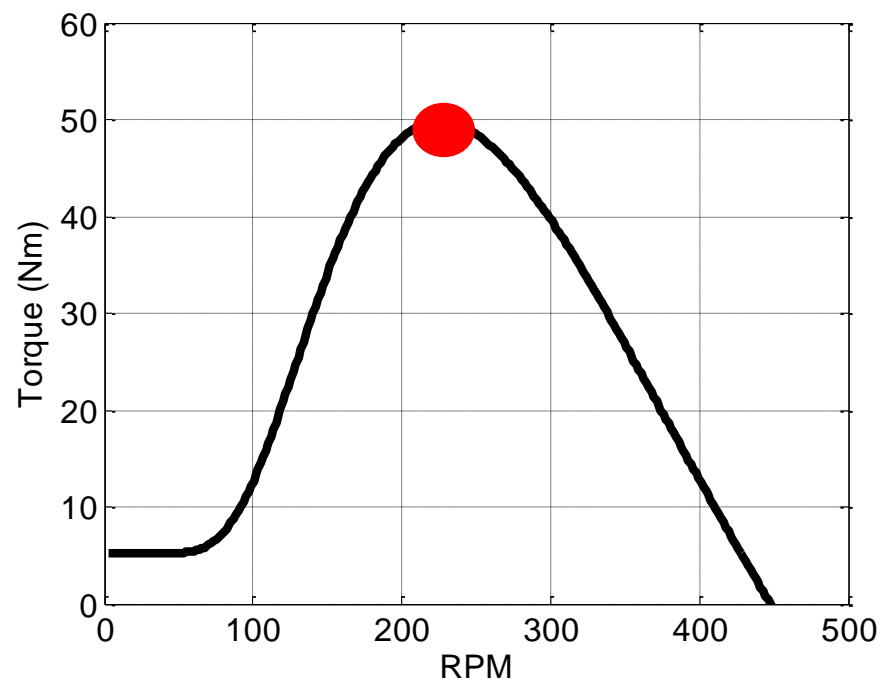
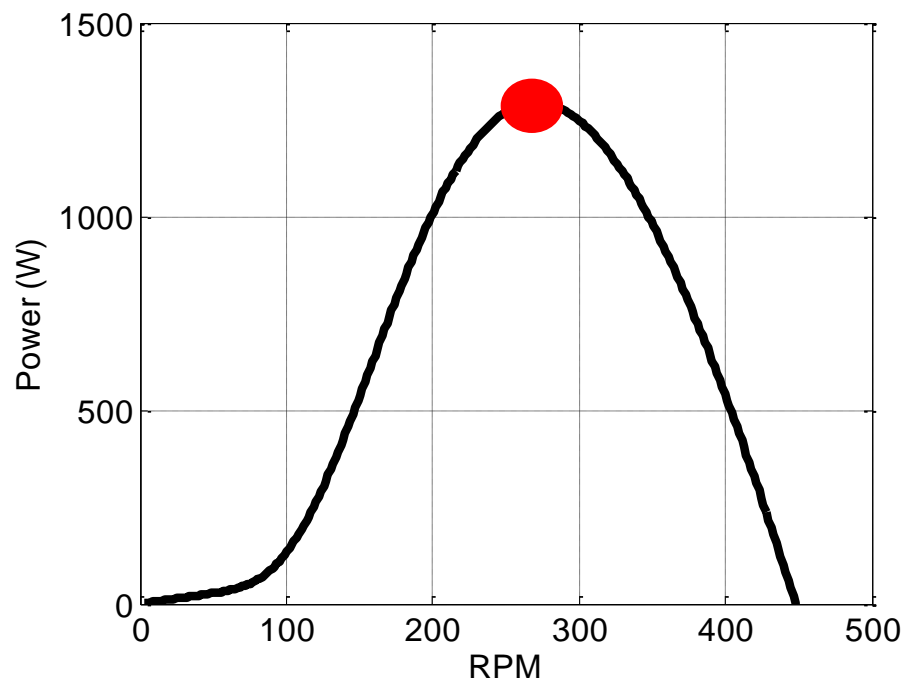
Operating point does not change if  $T_g = T_m$ ,  
but  $T_g$  is determined by the generator and its load





# Rotational Dynamics

What happens if generator torque suddenly increases to 55 Nm?

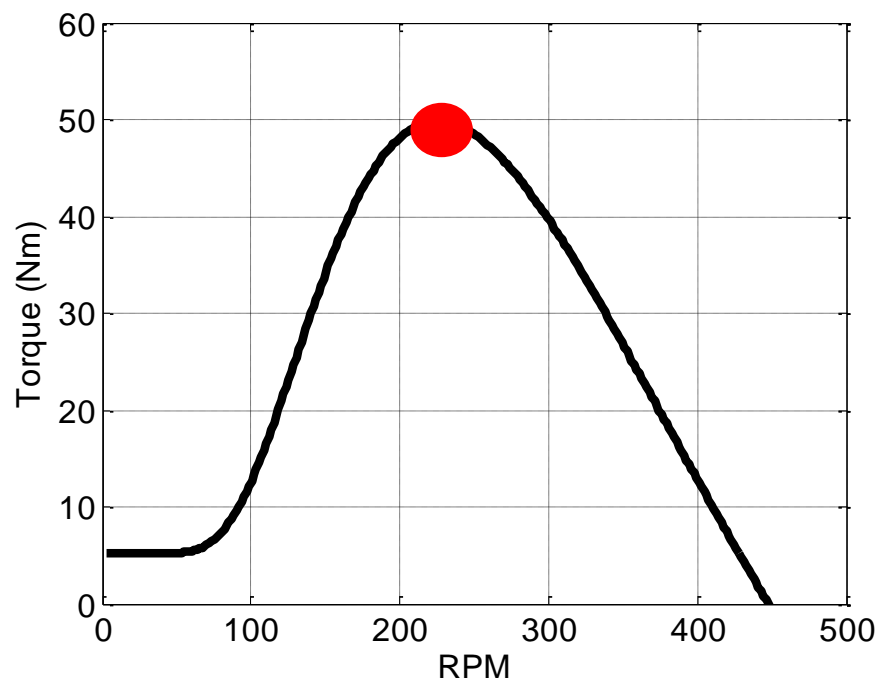
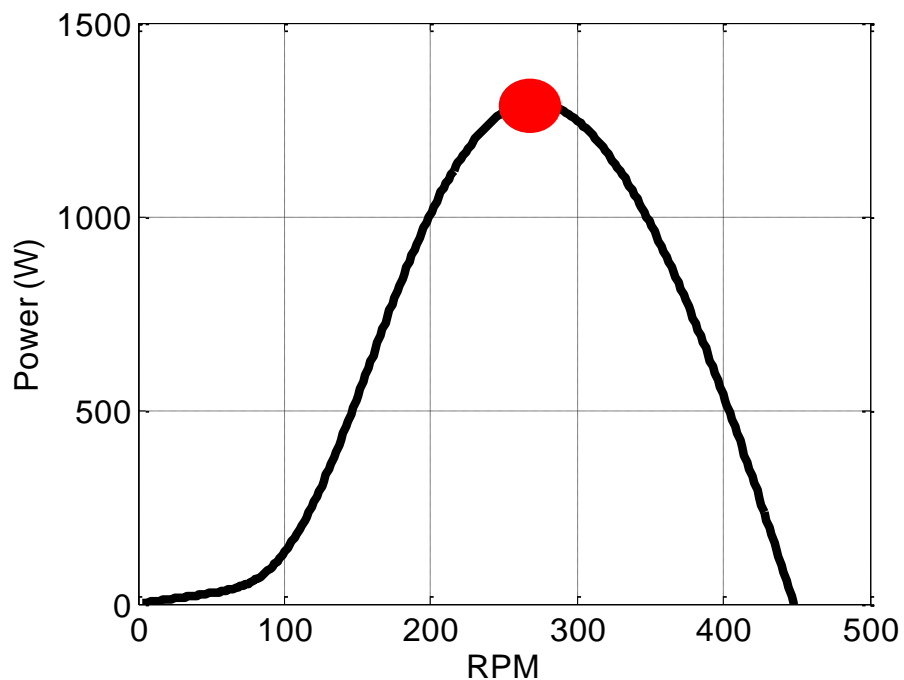




# Rotational Dynamics

$T_g > T_m$ , so generator slows down

If generator load is constant torque, wind turbine will eventually stop

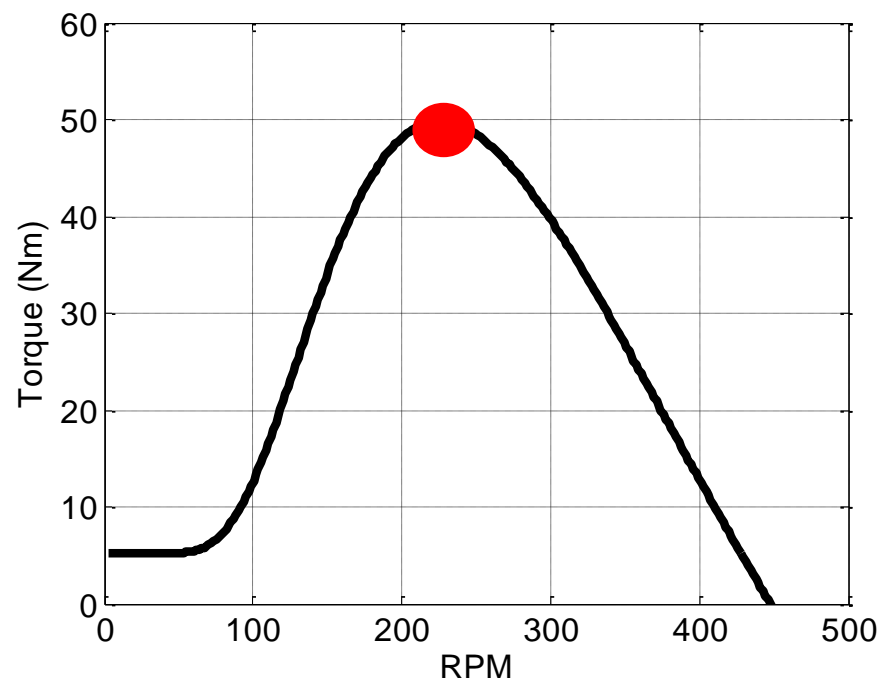
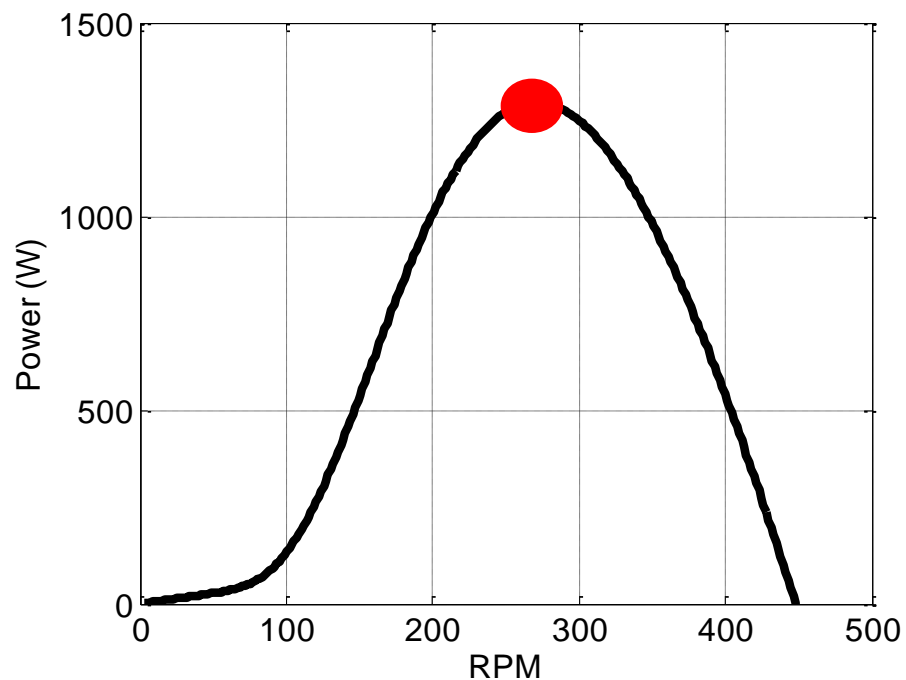






# Rotational Dynamics

What happens if generator torque suddenly decreases to 20 Nm?

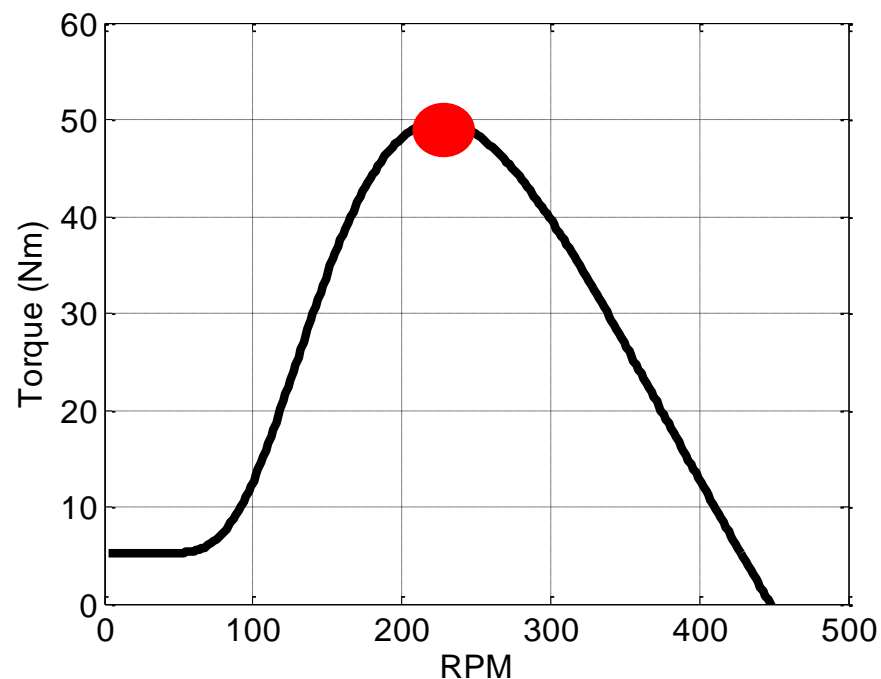
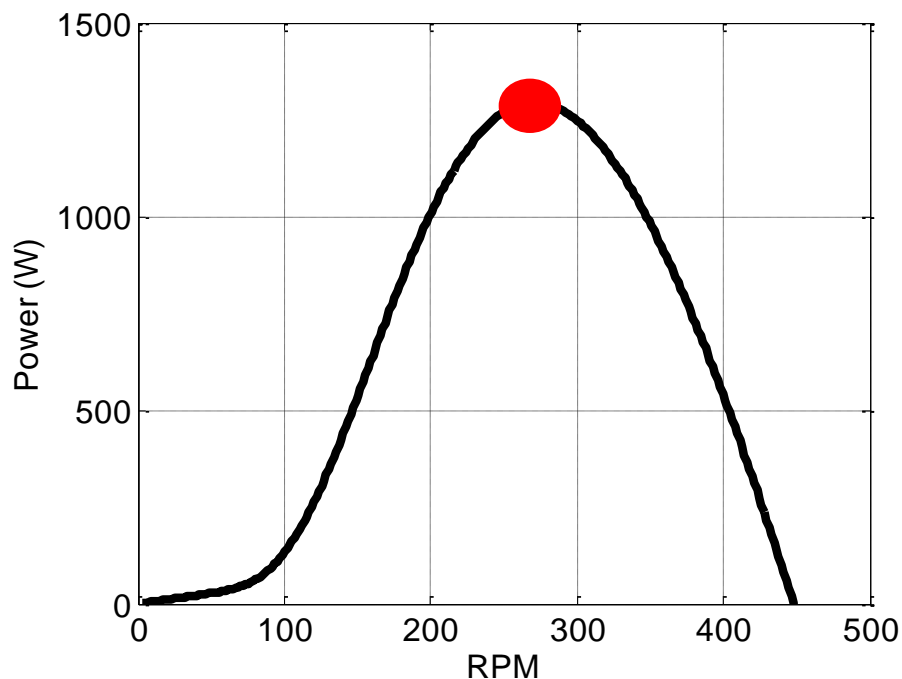




# Rotational Dynamics

$T_g < T_m$ , so generator speeds up

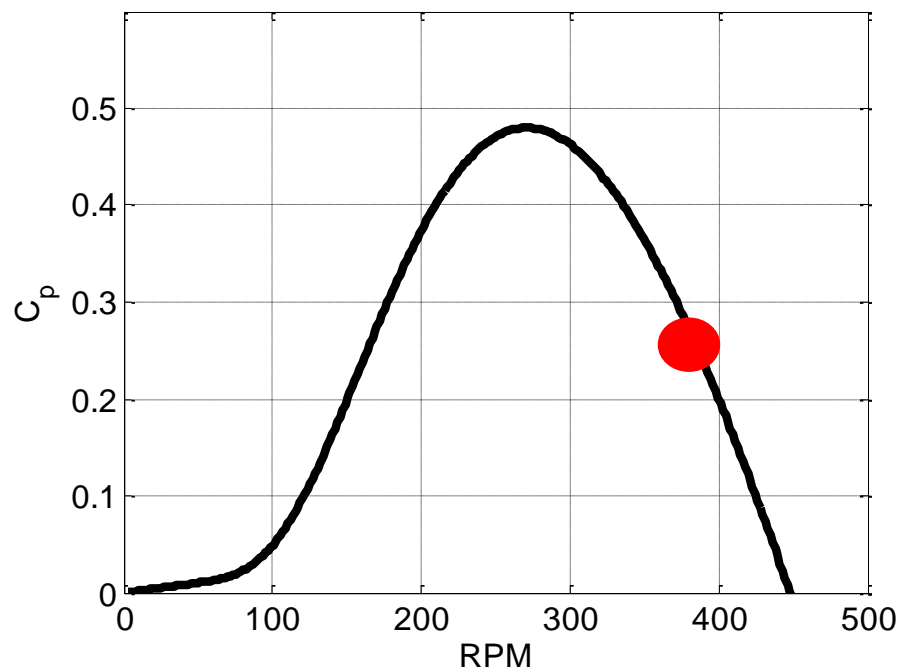
If generator load is constant torque, wind turbine will reach equilibrium point (but is operating inefficiently)





# Rotational Dynamics

Operating point is sub-optimal (overspeed)





# Generator Characteristics

- Battery loads are not constant torque
- Need to match wind turbine blades with generator characteristics

